

A Speech Cum Audio Controlled Robotic System Development For Generic Purposes

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Abstract

In this paper, the project titled "Voice-Controlled Bluetooth-Controlled Obstacle-Avoiding Robot" outlines a robotic system designed for control via both voice commands and Bluetooth communication. This robot is not only capable of obstacle detection, enabling it to navigate and circumvent barriers, but it also responds to voice instructions, offering users an interactive mode of control. Additionally, the Bluetooth feature facilitates remote operation through devices like smartphones. In essence, this project amalgamates voice recognition technology, wireless communication, and obstacle avoidance algorithms to create a versatile and engaging robotic platform. The work carried out is the second semester mini-project by the students of Electronics & Communication Engineering under the guidance of the faculties.

Introduction

The creation of a voice-controlled humanoid robot represents a complex project where various components seamlessly integrate. At its core, this endeavor involves constructing a physical humanoid robot equipped with advanced hardware and software capabilities. On the hardware front, this encompasses the design and assembly of the robot, including the incorporation of servos, sensors, microphones, and speakers. These integral components enable the robot to move, perceive its surroundings, process spoken commands, and respond through speech.

Creating a voice-controlled humanoid robot is a multifaceted venture that harmonizes the realms of robotics, artificial intelligence, and human-computer interaction. Its applications are diverse, ranging from aiding individuals with various tasks to delivering information and entertainment. This field is in a state of perpetual evolution, perpetually advancing through ongoing research and technological breakthroughs.

Literature review

In a world increasingly driven by automation and smart technology, the development of speech-controlled and audio-responsive robotic systems represents a groundbreaking frontier in robotics and artificial intelligence. This project aims to explore and advance the creation of a versatile and adaptive speech cum audio-controlled robotic system, designed for generic purposes. Such a system holds immense promise in a wide range of applications, from home automation and healthcare to industrial operations and beyond. This comprehensive two-page introduction provides an overview of the project, its significance, objectives, scope, and the multidisciplinary nature of this pioneering endeavor.

The Significance of Speech Cum Audio Control in Robotics

The fusion of speech and audio control with robotics presents a monumental shift in human-robot interaction. It is a technological leap that promises more intuitive, flexible, and user-friendly engagement with machines. As voice recognition and audio processing technology continue to advance, the opportunities for applying these capabilities to robotics are virtually boundless. The project's significance lies in its potential to democratize access to and utilization of robotic systems for a broader audience, transcending the barriers of traditional control methods and making robotics more accessible and adaptable in various settings.

Project Objectives

The primary objectives of this project are two-fold, viz. [17]-[20],

Robotic System Development: The core mission is to design and construct a state-of-the-art robotic system with hardware and software components capable of understanding and responding to human speech and audio commands. This entails integrating microphones, speakers, processors, and an array of sensors to create a sophisticated robotic platform.

Speech and Audio Control: In parallel, the project aims to develop advanced speech recognition and audio processing algorithms. These algorithms should enable the robot to comprehend spoken instructions and sound cues and translate them into meaningful actions, thus facilitating robust human-robot communication.

Scope of the Project Work

The scope of this project is extensive and multifaceted [13]-[16]

Hardware Development: The creation of a physical robotic system that encompasses mechanics, electronics, and sensors for movement, perception, and communication.

Software Development: The design and implementation of complex software algorithms for speech recognition, audio processing, and artificial intelligence to enable the robot to interpret and act upon audio inputs.

Integration: The seamless integration of hardware and software components to create a holistic robotic system capable of audio-driven interaction.

Adaptability and Versatility: The project endeavors to create a robotic system that can be adapted for diverse generic purposes. Whether it's assisting individuals with daily tasks, serving as a communication medium, providing entertainment, or aiding in industrial processes, this robotic system aims to be versatile in its applications.

Interdisciplinary Collaboration

The development of a speech cum audio-controlled robotic system is inherently interdisciplinary, drawing upon elements of robotics, computer science, artificial intelligence, signal processing, and human-computer interaction. The project thus necessitates collaboration among experts in these fields, fostering an environment where innovation and cross-disciplinary insights can flourish [9]-[12].

Potential Applications and Ongoing Advancements

The applications for a speech cum audio-controlled robotic system are broad and ever-evolving. These robots can be deployed in healthcare settings to assist individuals with disabilities or the elderly. In home automation, they can control appliances, provide information, and enhance security. In industrial scenarios, they can automate repetitive tasks and improve safety. As the project progresses, ongoing research and technological advancements will likely expand the capabilities and applications of such systems, pushing the boundaries of what is currently possible [5]-[8].

Conclusions

In conclusion, the project on speech cum audio-controlled robotic system development for generic purposes is poised to redefine how humans interact with and utilize robotic technology. By harnessing the power of voice recognition and audio processing, this project aims to create a transformative tool with a diverse range of applications. It represents a promising leap forward in the domain of robotics and human-robot interaction, promising to make the benefits of advanced robotics accessible to a wider audience while continually pushing the boundaries of technological possibility [1]-[4].

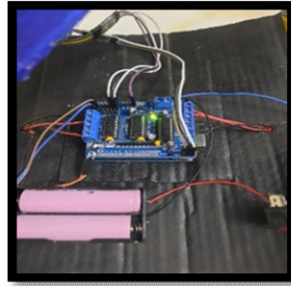


Fig. 1 : Hardware connections done

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